

Neural Volumetric Object Selection (NVOS)

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(* indicates alphabetic order)

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https://jason718.github.io/nvos





Task: object selection in neural volumes

Selecting objects in 3D neural volumes based on 2D user input

- 3D neural volumes: MPIs [Szeliski and Golland 1998] or NeRFs [Mildenhall et al. 2020]
- 2D user input: 2D scribbles in one view





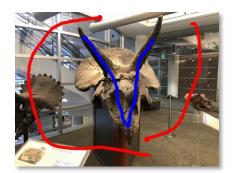




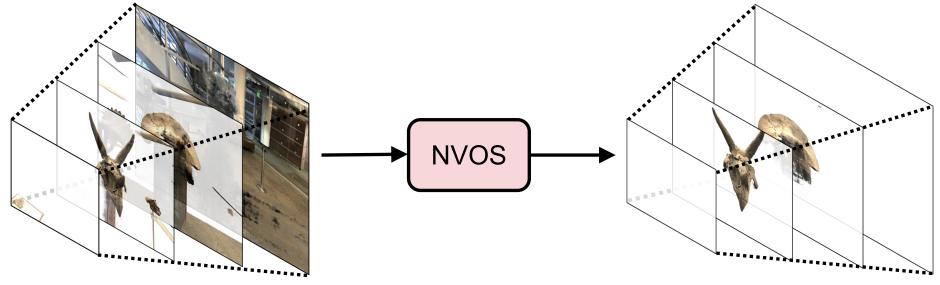
Approach: Overview



Input: multi-view images



Input: 2D scribbles



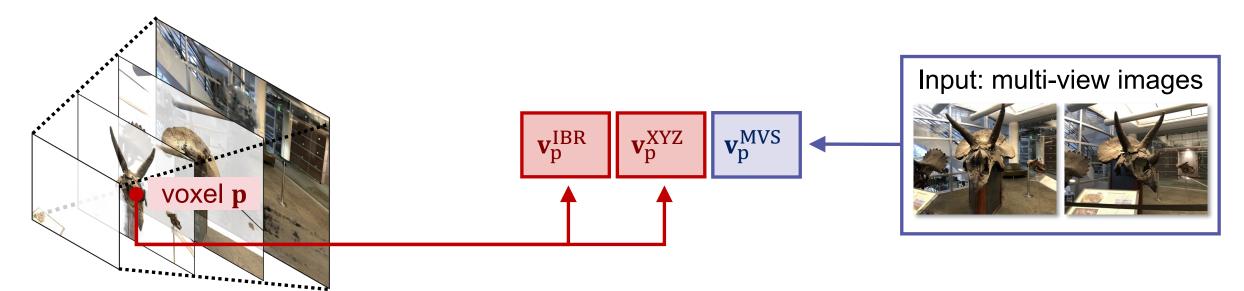
Input: learned volumetric representation

Goal: 3D foreground segmentation





Voxel feature



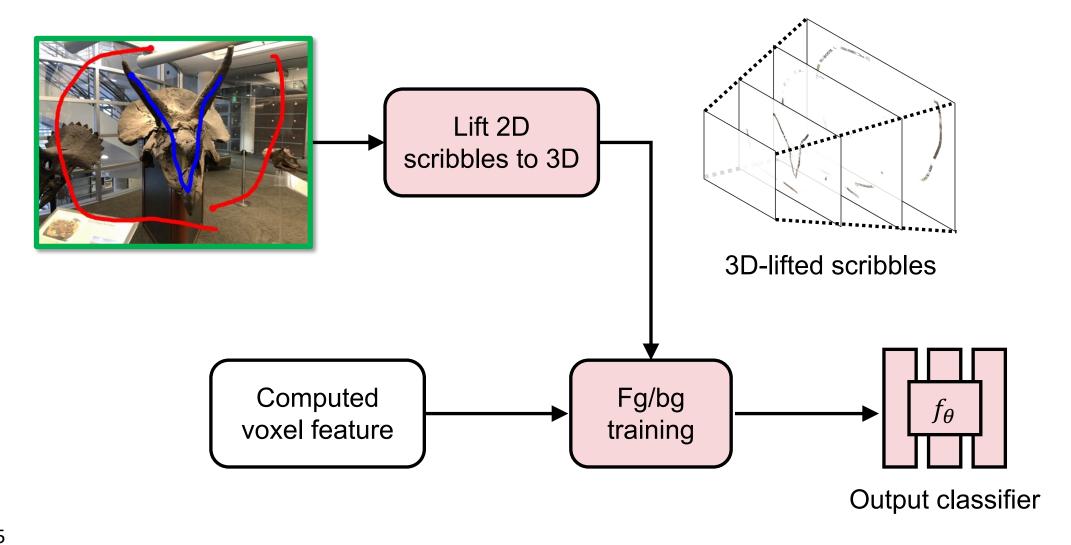
Voxel feature embedding $\mathbf{v}_p = [\mathbf{v}_p^{IBR}; \mathbf{v}_p^{IBR}; \mathbf{v}_p^{IBR}]$

- \mathbf{v}_{p}^{IBR} : discretized neural feature
 - MPI: NeX [Wizadwongsa et al. 2021] / NeRF: PlenOctree [Yu et al. 2021]
- \mathbf{v}_{p}^{XYZ} : 3D positional encoding feature
- $\mathbf{v}_{p}^{\text{MVS}}$: multi-view image feature embedding, following MVSNet [Yao et al. 2018]





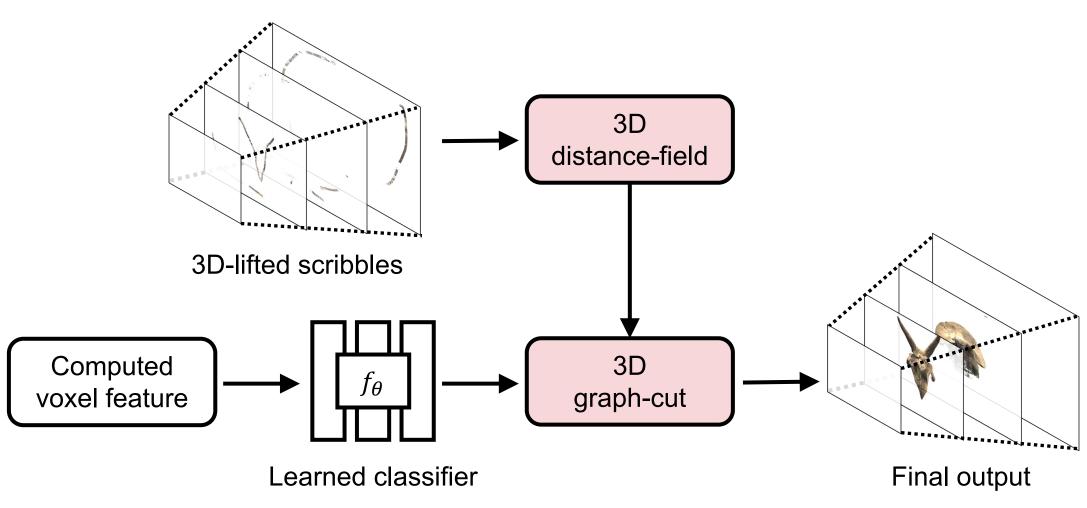
Training







Post-processing

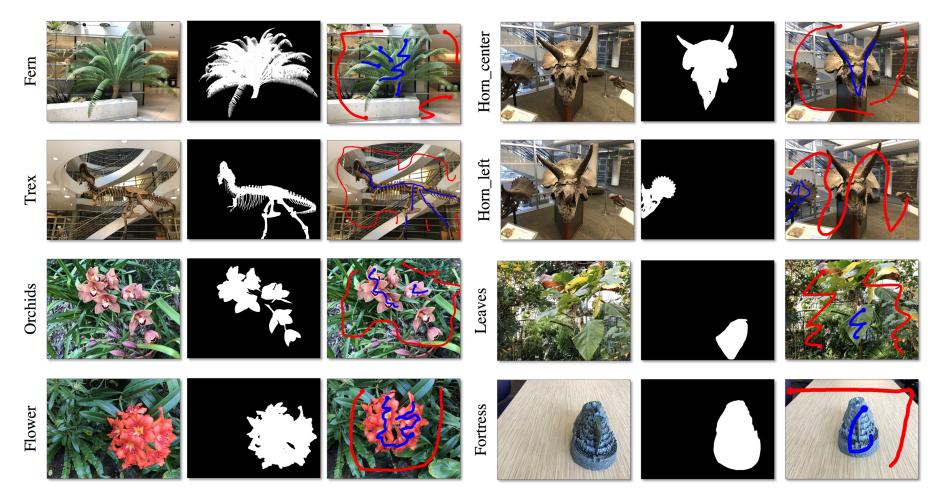






Dataset

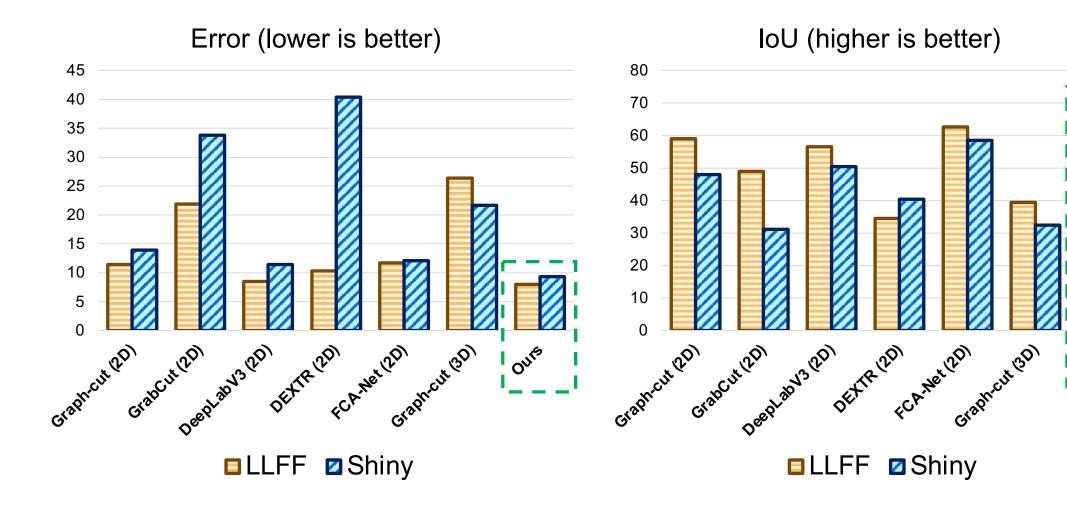
We annotate LLFF [Mildenhall et al. 2019] / Shiny [Wizadwongsa et al. 2021] with masks & scribbles





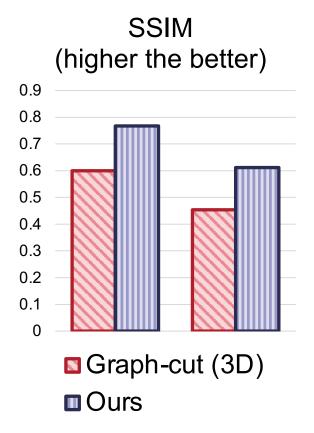


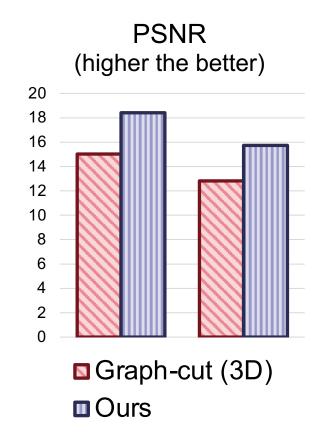
Results: 2D mask evaluation

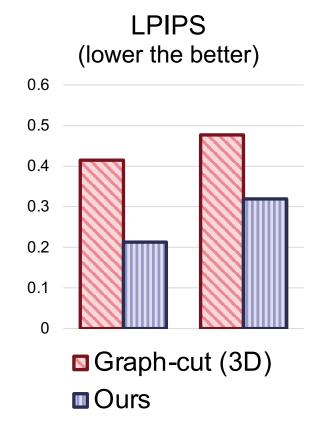




Results: novel-view object rendering

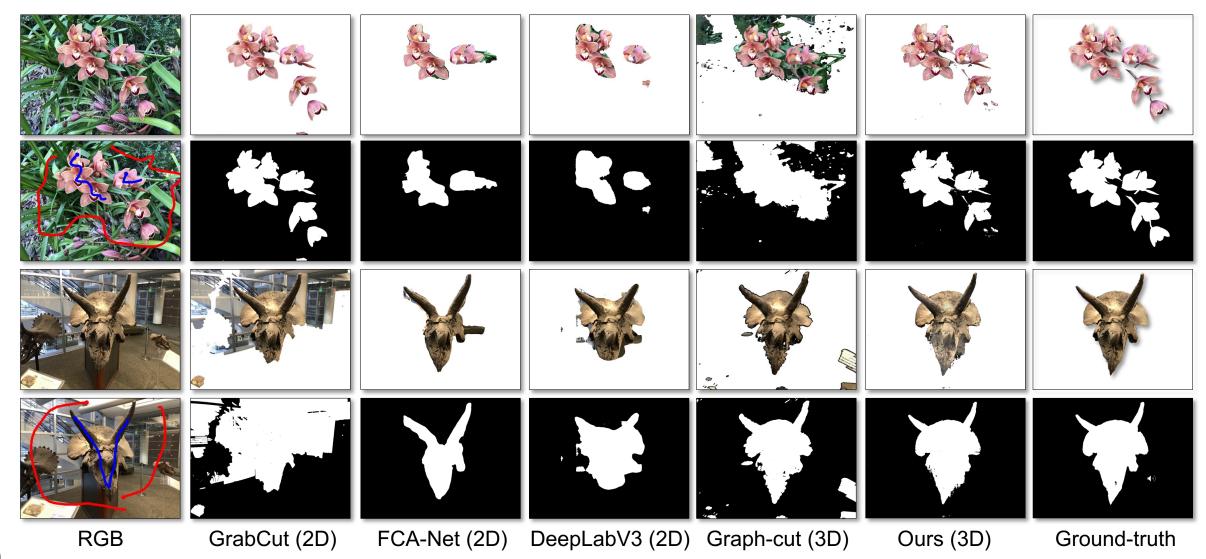








Results

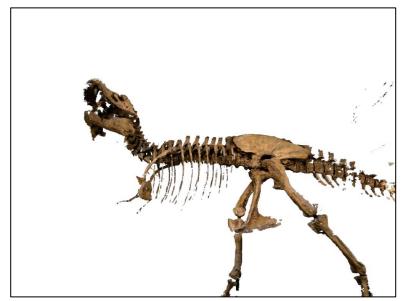




Thanks!

Please visit the poster session 2.1 at 10am-12:30pm on June 22!





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