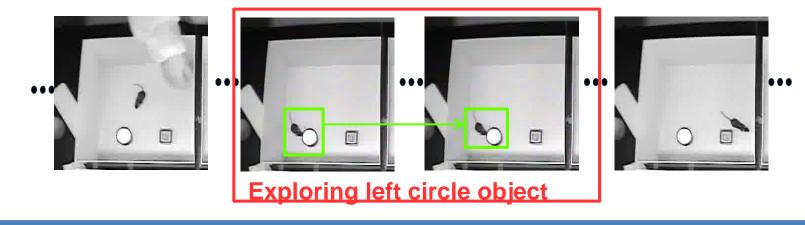
# UCDAVIS UNIVERSITY OF CALIFORNIA

# Who moved my cheese? Automatic Annotation of Rodent Behaviors with Convolutional Neural Networks

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### Problem

In neuroscience, understanding animal behaviors is key to studying their memory patterns.

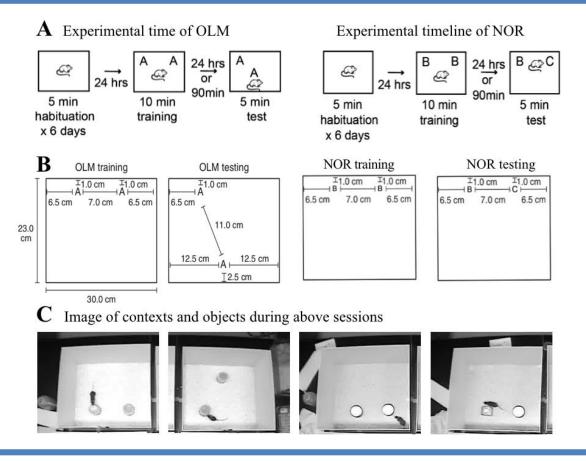


### **Motivation and Goal**

Neuroscience researchers hand-label videos because existing automated systems are unreliable.

- Previous work [Noldus et al. 2001, Burgos-Artizzu et al. 2012, Giancard et al. 2013, Lorbach et al. 2015, ...] or commercial software [2] mainly rely on object tracking and are prone to drifting.
- We instead treat this as a per-frame action classification problem.
- We also want to release a better annotation and visualization UI for neuroscience community.

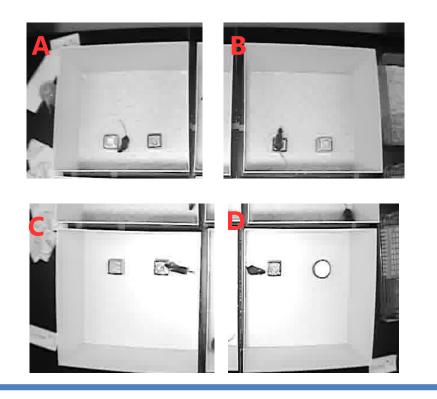
#### **Experimental setup**



- We study rodent memory by conducting Object Location Memory (OLM) and Novel Object Recognition memory (NOR) tasks.
- We need to count the exploration time for each object to find the rodent's preference patterns.

### Challenges

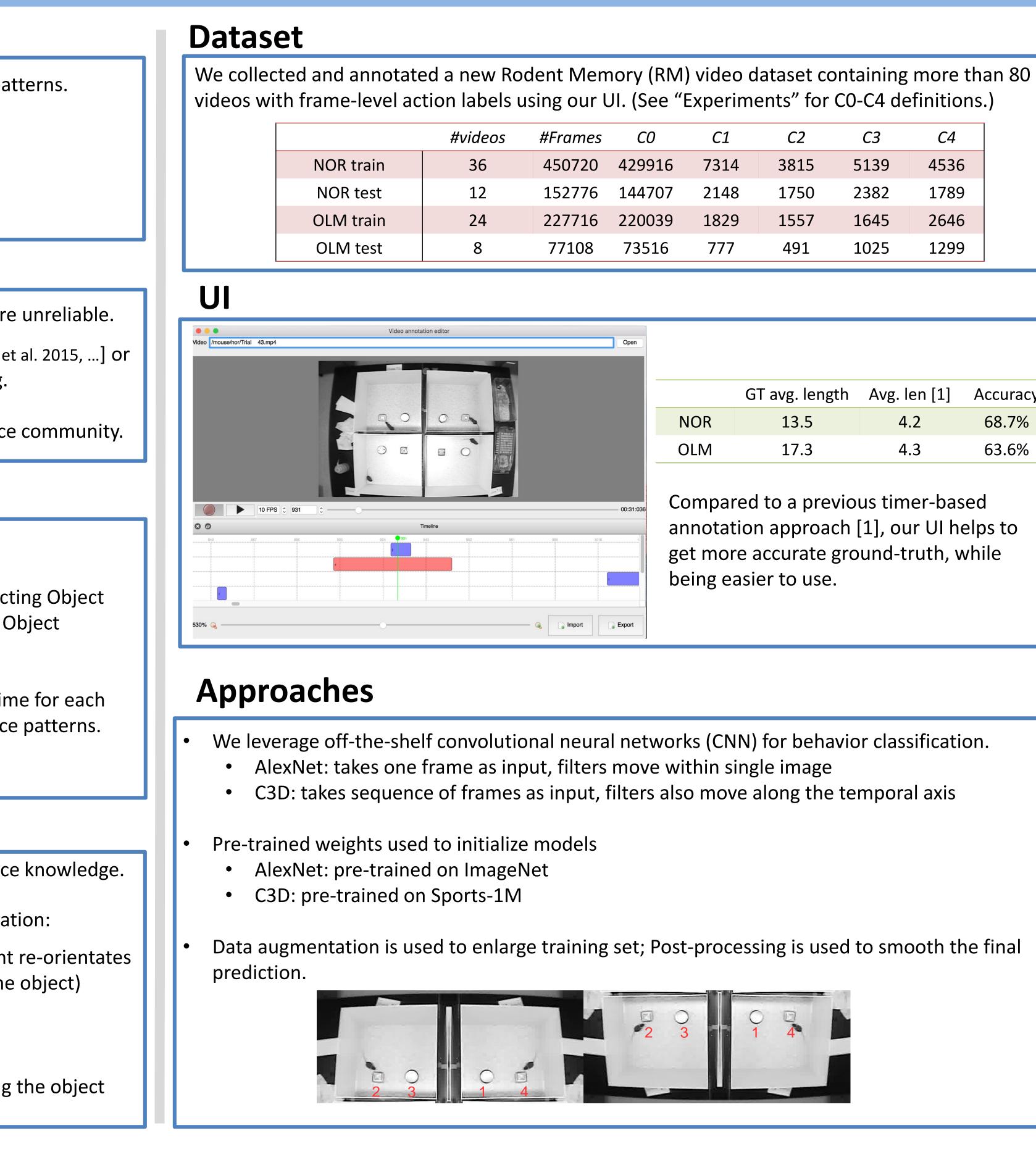
Strict criteria to judge whether an action is exploration or not based on neuroscience knowledge.



For example, below cases do not count as exploration:

A. Not approaching the object (e.g., if the rodent re-orientates itself and the nose accidentally comes close to the object)

- B. On top of the object
- C. Looking over the object
- D. Repetitive behavior like digging close or biting the object



	С2	С3	С4
4	3815	5139	4536
8	1750	2382	1789
9	1557	1645	2646
,	491	1025	1299

GT avg. length	Avg. len [1]	Accuracy
13.5	4.2	68.7%
17.3	4.3	63.6%

Compared to a previous timer-based annotation approach [1], our UI helps to get more accurate ground-truth, while

#### Experiments

We compare against a widely-used commercial software Any-Maze [2], which tracks rodent body key-points.

Per-frame Classification Accuracy (%)												
	Any-maze [2] Alex-ne		Alex-net	C3D(d=3)	C3D(d=5)		C3D(d=9)					
	NOR	NOR 78.34 93.17		93.17	89.30	87.	.54	77.74				
	OLM 74.25 95.24		95.24	91.98	83.03		73.39					
		NOR	predic	tion				OL	M predie	ction		
ning	87.74	3.84	2.60	3.49	2.33	C0: Nothing	87.85	2.66	1.51	4.70	3.27	പ
rcle	0.23	99.44	0	0.19	0.14	C1: Left circle	7.34	92.66	0	0	0	rou
iare	1.26	0	95.94	0.06	2.74	C2: Right circle	0.81	0	99.19	0	0	GroundTruth
rcle	3.74	0	0.04	96.22	0	СЗ: Тор	0.68	0	0	99.32	0	uth
are	5.76	0.11	0	0	94.13	C4: Bottom	0.38	0	0	0	99.62	
C0: Nothing C1: Left circle C2: Left square C0: Nothing C0: Nothing C0: Nothing C0: Nothing C0: Nothing C0: Nothing C0: Nothing												
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CO: Nothing	87
C1: Left circle	0
C2: Left square	1
C3: Right circle	3
C4: Right square	5

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		Per	-frame	e Classifi	cation Accura	icy (%)					
	Any	/-maze	[2]	Alex-net	C3D(d=3)	C3D(	d=5)	C3D(d=	:9)		
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#### Qualita



Our model detects the various rodent explorations across a wide range of videos.

Neuroscience Experiments										
	Corre	elation coef	ficient with (	GT	• T1, T2: exploration time of two					
	Annotator	T1	T2	DI	objects					
	Any-maze	0.67	0.659	0.599	<ul> <li>Discrimination Index:</li> </ul>					
	Ours	0.79	0.952	0.845	DI = (T1 - T2) / (T1 + T2)					
Our model is reliable enough to replace human annotations in neuroscience experiments.										

#### References

- 1. A. V. Ciernia and M. A. Wood. Examining object location and object recognition memory in mice. In Current Protocols in Neuroscience, 2014.
- Any-maze behavioral tracking software. http://www.anymaze.co.uk/index.htm.

